

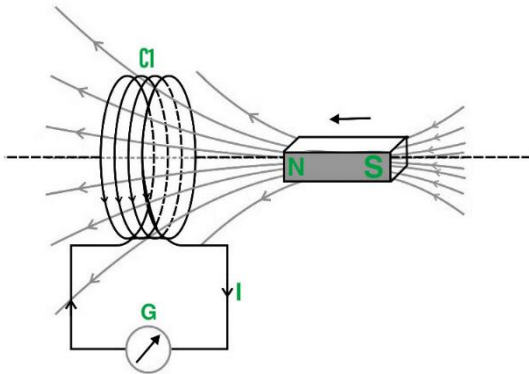
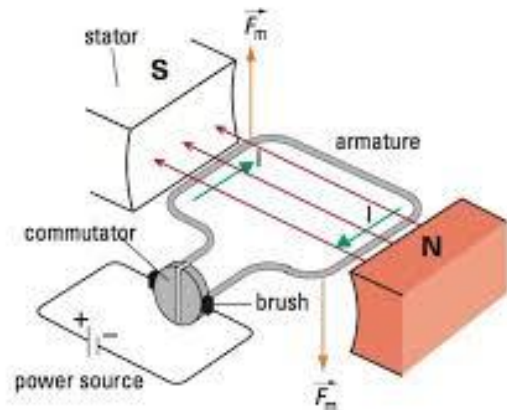
Lesson 8.3 - Generators and Back EMF

Unit 8: Electromagnetic Induction

Transitioning into the Generator:

Recall:

- ❖ A **current** in a wire produces a **magnetic** field.
- ❖ In a **motor**, this magnetic field interacts with an **external** field to create a **force** and cause **rotation**.



- ❖ Conversely, if we **mechanically move a conductor (armature)** in a magnetic field, an EMF is induced (**Faraday's Law**).

$$\mathcal{E} = -N \frac{\Delta \Phi}{\Delta t}$$

The Generator:

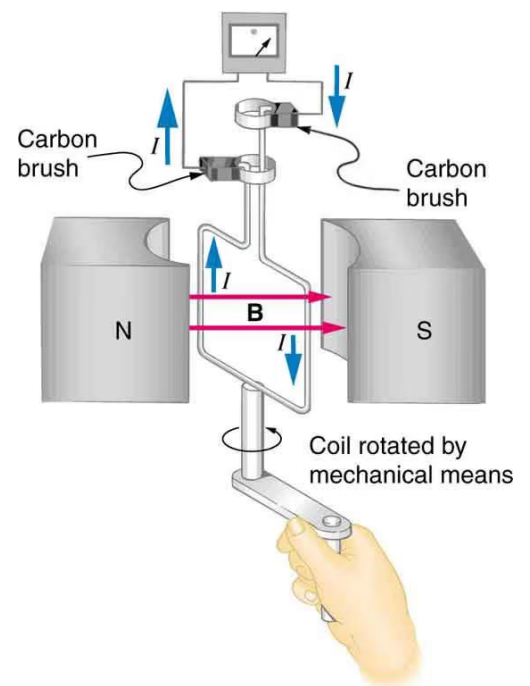
Electric motors and generators act on the same principles from different perspectives.

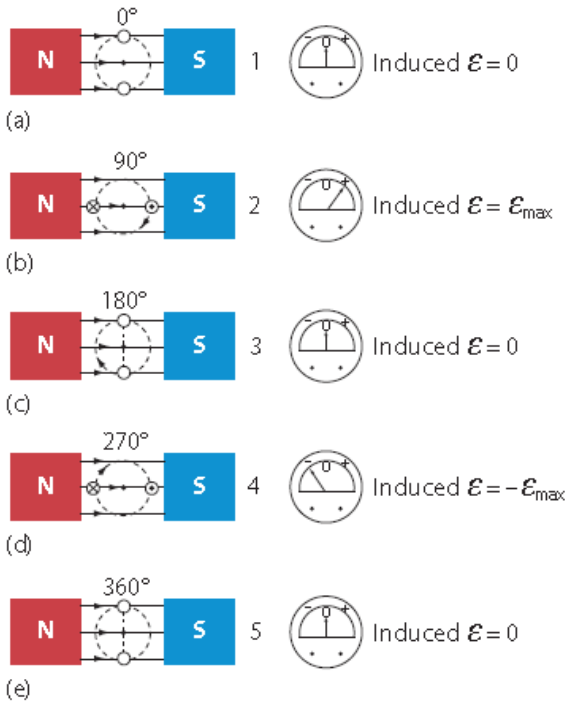
Electric motor: **electrical** energy -----> **mechanical** energy

Electric Generator: **mechanical** energy -----> **electrical** energy

[Simulation 1](#) and [Simulation 2](#)

- **Mechanical** source rotates the **armature** (coil) in external magnetic field.
- The change in **flux** produces an **induced EMF**
- Direction of induced current follows **Lenz's Law** (opposes the change).
 - **Use 2nd right-hand rule**

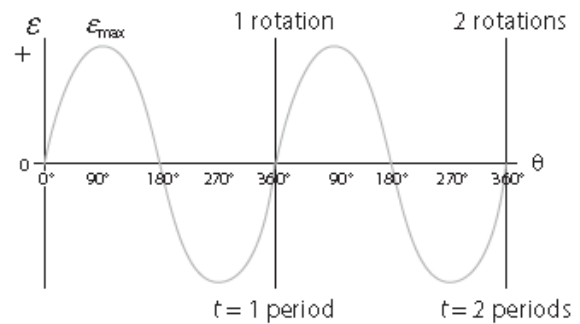




EMF (voltage) is **maximum** when the armature arms are **horizontal** because their motion is **perpendicular** to the magnetic field

EMF is **zero** when they are **parallel**

****think about a swing where parallel is the highest you go and stop for a split second (=0)*



Induced EMF of one "arm" of the armature:

$$\varepsilon = \vec{B}l\vec{v}\sin\theta$$

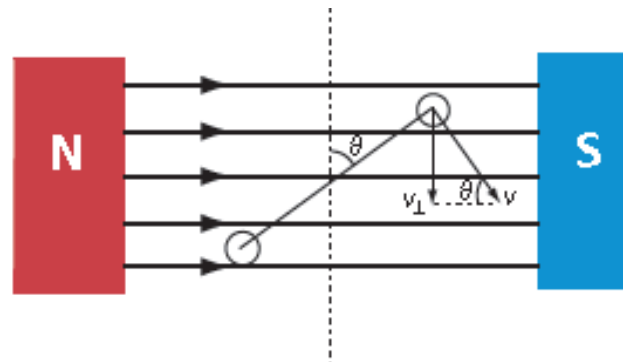
Induced EMF of two "arms" of the armature:

$$\varepsilon = 2\vec{B}l\vec{v}\sin\theta$$

With N loops of wire:

$$\varepsilon = 2N\vec{B}l\vec{v}\sin\theta$$

$$\mathcal{E} = \mathcal{E}_{\max} \sin\theta$$



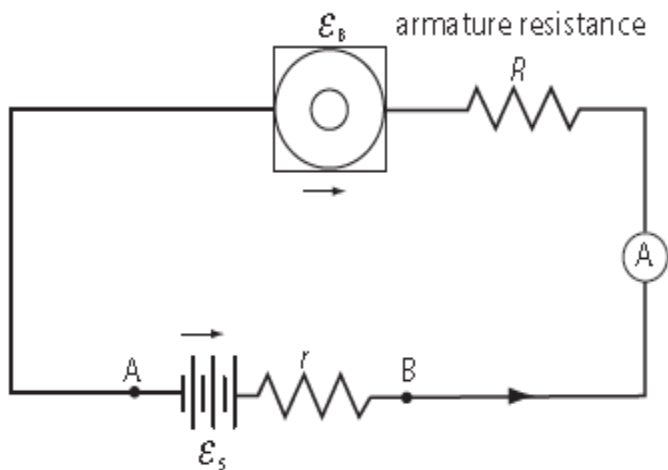
List all the generators you can think of that turn mechanical rotation into electrical energy:

Back EMF:

Consider what know:

- A **current** in the armature produces **motion** (motor effect).
- Changing **flux** or moving a **conductor** induces an EMF (**Faraday's Law**).
- The induced EMF creates a **magnetic** field that **opposes** the change (**Lenz's Law**).

Back EMF: Since motion induces an **opposing** EMF (Lenz's Law), the induced EMF in a motor must oppose the **current** that drives it.



$\mathcal{E}_s$ = EMF source to motor
 r = internal resistance of the source

$\mathcal{E}_B$ = Back EMF

R = resistance of armature (coil).

We can apply Kirchhoff's Law to consider net voltage:

$$\mathcal{E}_s - Ir - IR - \mathcal{E}_B = 0$$

$$\mathcal{E}_B = \mathcal{E}_s - Ir - IR$$

Terminal Voltage between A and B = V_{AB} or V_T or $\mathcal{E}$

$$\mathcal{E}_B = V_{AB} - IR$$

or on your formula sheet

$$V_{\text{back}} = \mathcal{E} - Ir$$

Show this video

Example 1: The armature windings of a DC motor have resistance of $10\ \Omega$. The motor is connected to a 120 V battery (no internal resistance). At full speed the back EMF is 108 V . Find the start up and full speed currents.

Start-Up:

$$\mathcal{E}_B = 0$$

$$\therefore V = IR$$

$$I = \frac{V}{R}$$

$$I = \frac{120\text{V}}{10\ \Omega}$$

$$\boxed{I = 12\text{A}}$$

Full Speed :

$$\mathcal{E}_B = V_{AB} - IR$$

$$I = \frac{V_{AB} - \mathcal{E}_B}{R}$$

$$= \frac{120\text{V} - 108\text{V}}{10\ \Omega}$$

$$\boxed{I = 1.2\text{A}}$$